

# >warpx.io

> Rapid IoT & Wearable Prototyping  
featuring Hybrid Architecture

Nicola La Gloria

Aaron Moore

warpx.io

# Overview

- Talk today focuses on the concepts learned by our team in developing prototypes in both IoT and wearables
- We will be presenting a solution that we developed with the support of leading companies in this industry
- Concepts used here can be applied to many platforms

# Why do we need to build small devices

- Start-ups/Companies/Makers/Researchers in the IoT and wearables are needing to build increasingly smaller electronics
- Can be required to prove concepts before getting approval/funding/etc, but how?
- To design this, they face challenges traditionally left to large companies with big budgets

# Challenges of building small

- Building form-factor devices introduces many new layers of complexity into the design. Not just electronics but also the enclosure and back-end connectivity, support peripherals, UX design, etc.
- Typical traditional design cycles for these systems are long
- Large customers have custom parts made just for them to help scale their designs. Resources not always available to broad audience

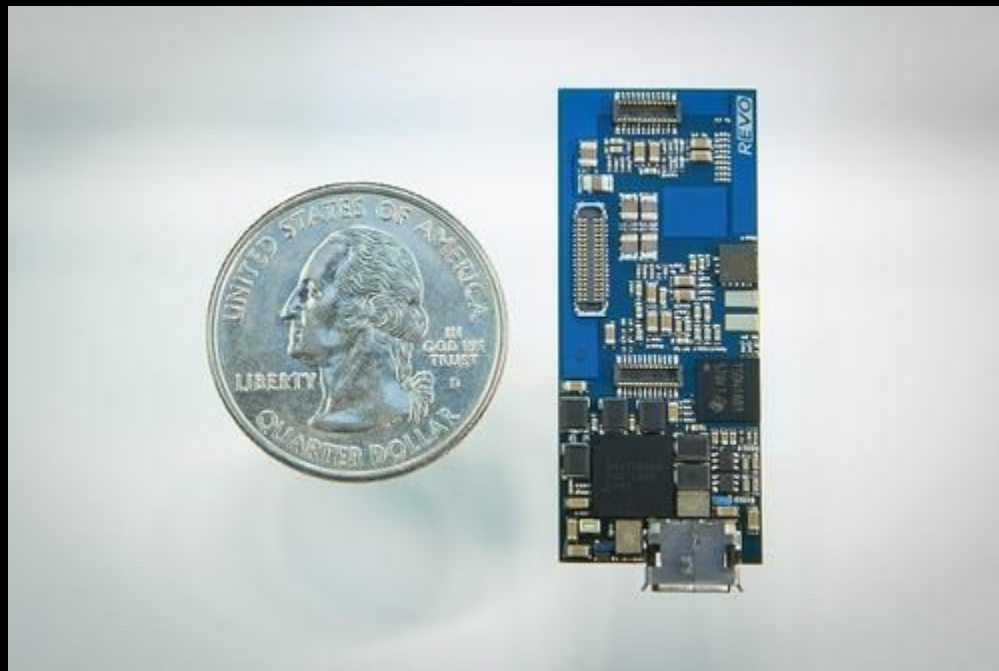
# Challenges of building small

- Need to give developers the right tools, same or similar to those used by big companies
- Existing tools that are fast, do not scale, or scale, but do not fit well for IoT & wearables due to missed considerations (driven by different market needs).
- We realized the need for a process that allows makers and professionals to #buildfast proof of concepts, reducing dev time and cost.

# MCU vs AP

- Designing with Microcontrollers vs an Application Processor is very different.
- Both are good choices and depends on the design of the Wearables or IoT device.
- However, APs can save valuable development time early in the design stage by providing a lot of functionality that is typically difficult to implement well on an MCU (reduces design time for prototypes).

# What we developed...



# warpx

- › The idea of **warpx** is the design of small form-factor, powerful embedded systems designed around an architecture we developed called Hybrid Design.
- › **warp\_0x01** is the first of this family of products designed and built by us.
- › Our hope/goal is to help pave way for the development of small and powerful computing devices integrated into wearables, sensors, and various other IoT devices.



# A Rapid prototyping toolbox

- › warp\_0x01 is the core upon which designs can be built and provides the part that is most difficult in terms of development (both design and manufacturing).
- › 80% of the needed functionality comes out of the box. Just add your sensor.
- › warp\_0x01 is **open**: Software, Hardware, BOM, schematics. You can manufacture it too.

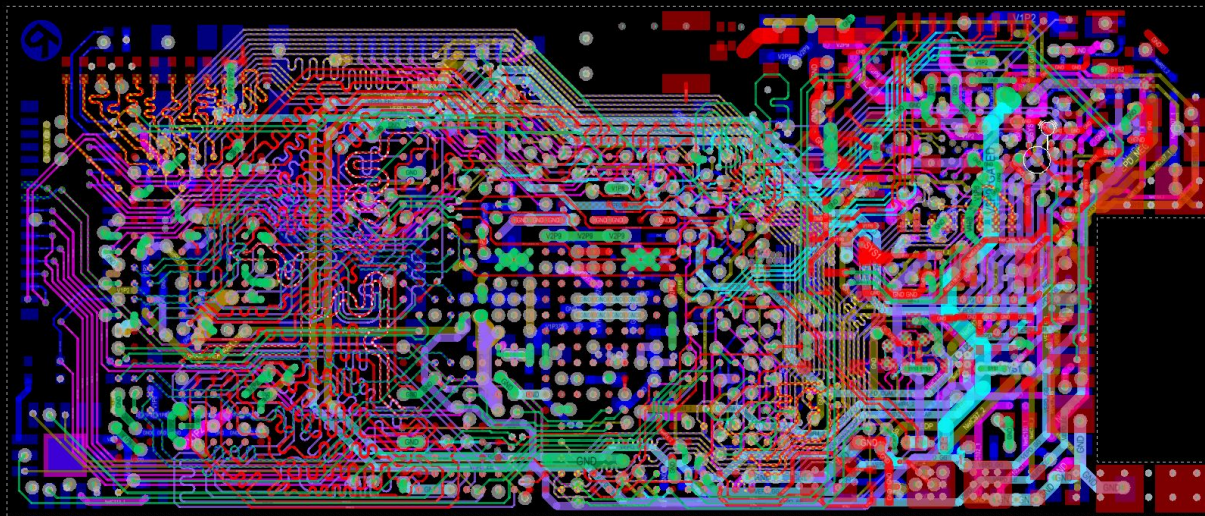
# warpx.io \0/

- › **warpx.io** is the community hub embracing today all the developers that actively developed the codebase.
- › Aims to be the home for makers, professionals, designers, developer, blogger working with these small devices and whoever wants to contribute to this project.

**Main contributors:** Diego Rondini, Ray Anderson, Jacob Postman, Otavio Salvador, Eric Nelson, David Clack, Elena Contini, Will Martindale, Nicola La Gloria, Aaron Moore

...& you :)

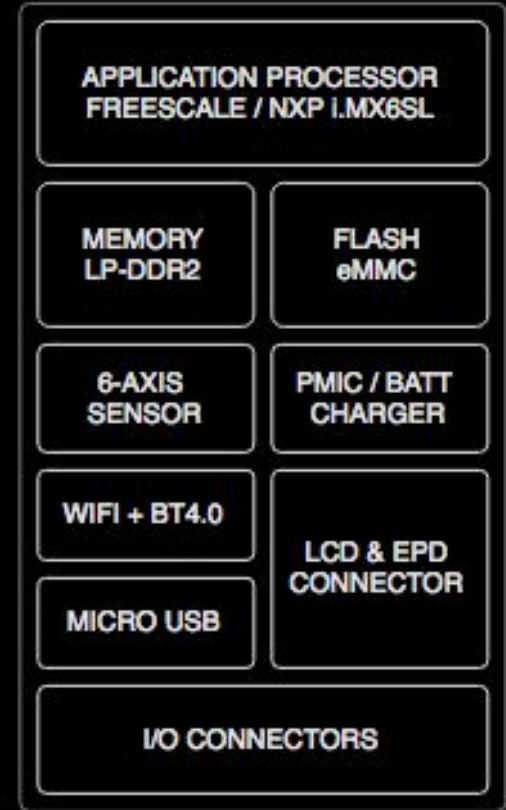
16mm



38mm

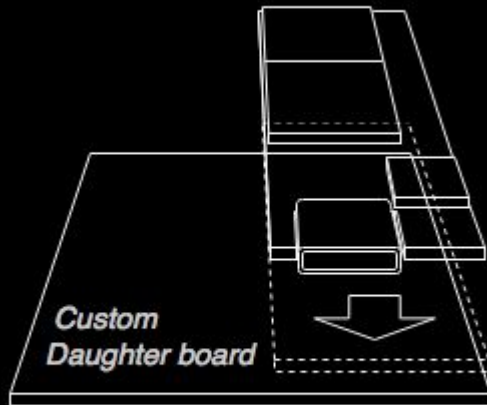
## Hardware Details:

- › Small form factor: 16mm x 38mm x 3.5mm  
(Board Area < 1 sq-in)
- › 10 Layer HDI PCB (0.4mm BGA, LGA, 0201)
- › 1Ghz ARM Cortex-A9 (Freescale i.MX6SL)
- › 512MB Memory + 4GB Flash
- › USB OTG, 6-axis ACC+Mag, PMIC, Wifi+BT/BLE
- › **B2B Expansion**



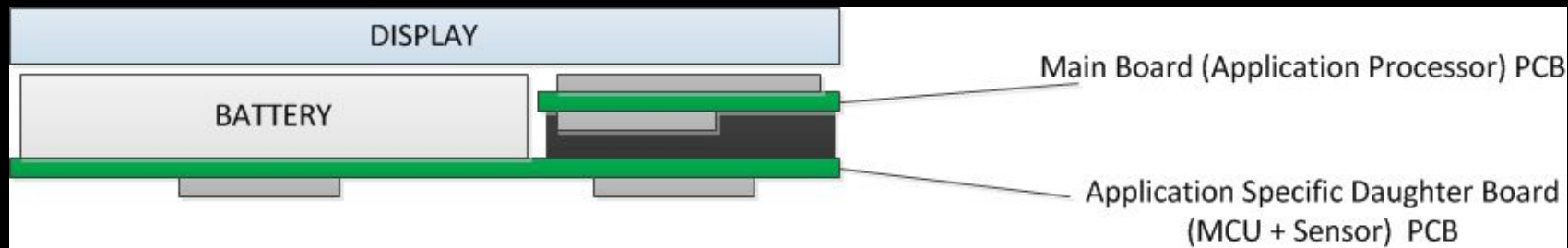
# Hybrid Architecture

- › Prototyping hardware with APs is hard, MCUs are much faster.
- › Hybrid Architecture responds to the need of having a design featuring the power of an AP and the low power capability of a MCU



# Hybrid Architecture

- › Mainboard (AP): reusable high performance core
- › Daughter Board (MCU): application specific payload (typically just a sensor)



# The Puzzle Game

## Hardware:

- › Warp
- › Daughter Board (can be custom)

## Development Tools:

- › Interposer Board

## Accessories:

- › Displays
- › Battery
- › Sensors (many)

## OS:

- › Yocto Linux
- › Android

## Software:

- › Java, Python

## I/O & Communication:

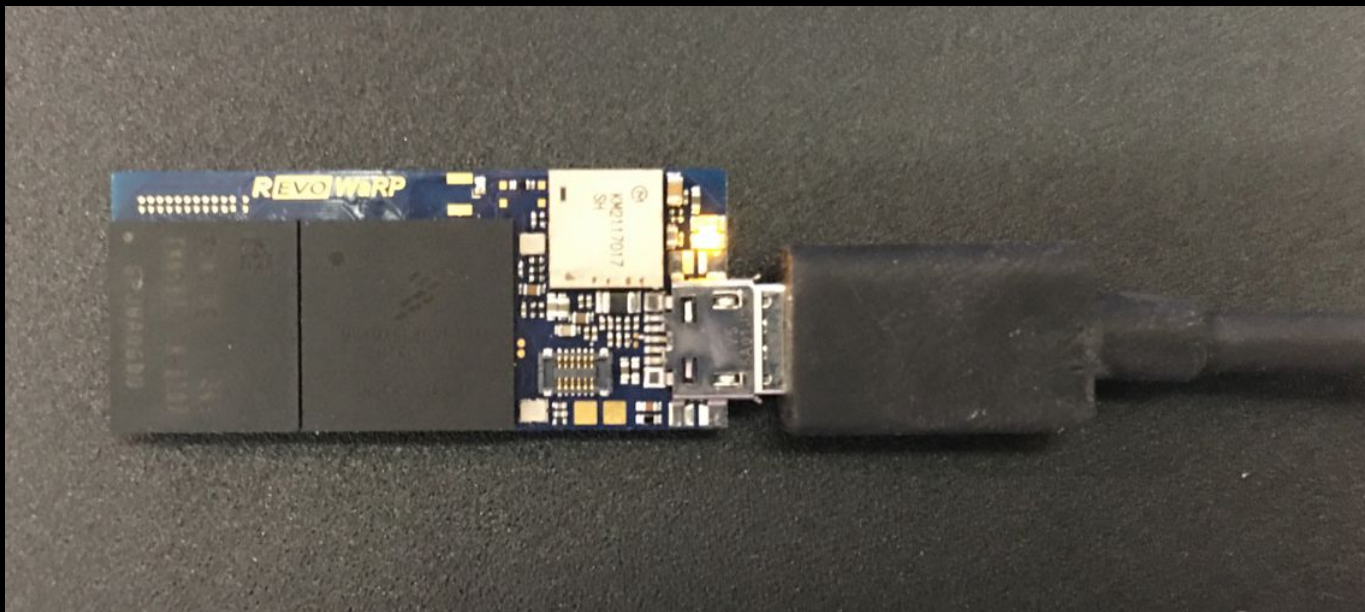
- › USB OTG
- › BT, BLE
- › WIFI 802.11 b/g/n
- › Ethernet & serial gadget

# Prototyping Scenarios

- › Using the puzzle pieces we assemble a variety of configurations that build up the prototype.
- › The steps and setups will help to determine your design needs and can be useful to prove the validity of a concept very early.
- › Using these methods, the focus is always on your application specific design needs, never on the design or re-development of tools.



# Get Started



# Get Started

- › **Hardware:** Warp
  - › **Software:** Yocto Linux
  - › **I/O:** WiFi, Serial Gadget
- 
- › At this stage, very similar to every other SBC (Rpi, Wandboard etc,) except that warp is  $\mu$ , very  $\mu$

# Get Started

- › Basic computing platform, perhaps as a gateway or hub.
- › Linux tools allow network code to be written easily
- › Can start to grab data (aggregate) from local devices (BT/WiFi) and processed this on-board (storage, algorithms, connection to cloud).

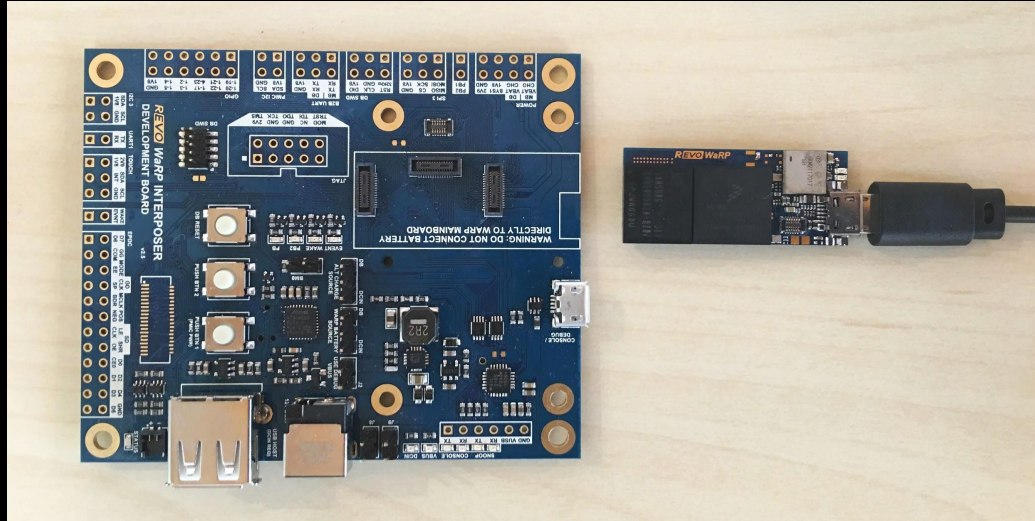
# Hacking Around

- › **Hardware:** Warp, Arduino
- › **Dev Tools:** Interposer Board
- › **OS:** Yocto Linux
- › **I/O:** WiFi, Serial Gadget
- › **Software:** Python

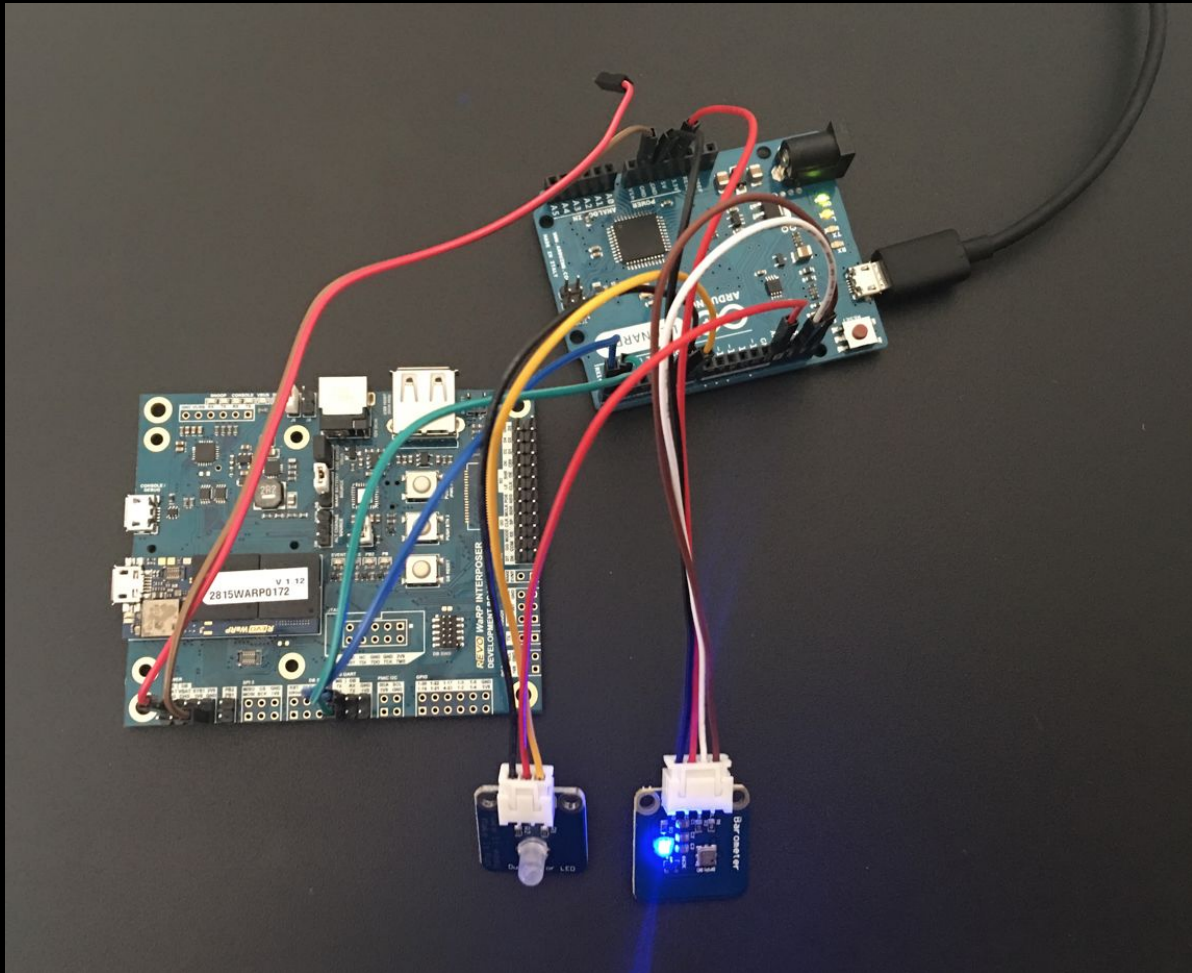
**Arduino** - off the shelf, simple to hook to warp without reinventing everything. Hands on with sensors and controls

**Python** - Real easy access to peripheral boards.

# Hacking Around



› the Interposer makes development faster & easier



# Hacking Around

- › Arduino or similar HW familiar to many developers. Keeps MCU code VERY simple for accessing sensor. Lots of existing code.
- › Many sensors to play with, but might not be the exact sensor you want to use. Benefit is no custom hardware is needed.
- › Few lines of code (both MCU and AP) gets data streaming from SENSOR -> MCU -> AP -> UI or Cloud
- › Problem is that it's too big to do anything small. That's OK.

# Prototype 0x01 (headless)

- › **Hardware:** Warp, custom sensor board (hooked to the interposer pin outs)
- › **Dev Tools:** Interposer Board
- › **OS:** Yocto Linux
- › **I/O:** WiFi, Serial Gadget
- › **Software:** Python, Java, APIs

**Value:** Early stage IoT headless edge device proof of concept && get application development started (issue is often the disconnection between hardware and software teams)



# Prototype 0x01: defining the API

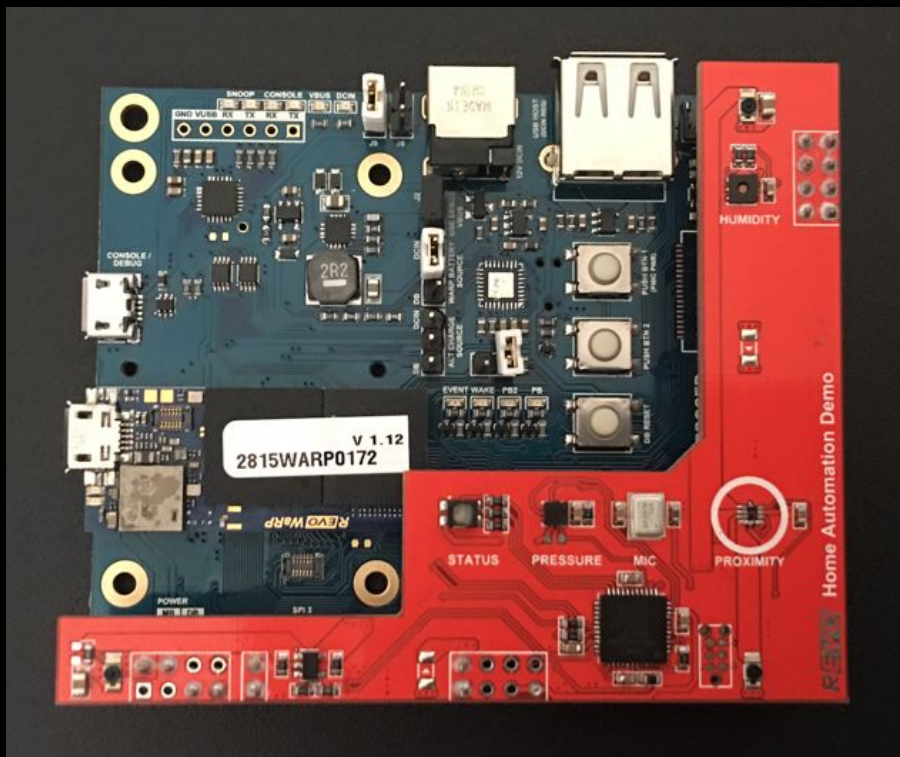
- › Define APIs
- › API is the **contract** between hardware and software

**Value:** hardware can continue to iterate and software development is not at the end of the cycle (as always :Q)

Example (JSON payloads):

```
{ "RGB_LED" : [R,G,B] }           //0-255 values for rgb
```

```
{ "TEMPERATURE" : FLOAT_C }
```



# Prototype 0x01 (headless)

- › Gets hardware functional with the application specific sensors onto a rough board that can be replicated easily. No wires
- › Easy and fast to develop hardware like this. Very low cost from hardware perspective.
- › Plugs into existing dev tools so application team can get access to hardware early.

# Prototype 0x02 (headful)

- › **Hardware:** Warp, custom sensor board (hooked to the interposer pin outs)
- › **Accessories:** Display
- › **Dev Tools:** Interposer Board,
- › **OS:** Yocto Linux
- › **I/O:** WiFi, Serial Gadget
- › **Software:** Python, Java, APIs

**Value:** Early stage IoT #HEADFULL edge device proof of concept.

# “Hello World” GUI code

```
import sys
from PyQt5 import QtWidgets

app = QtWidgets.QApplication(sys.argv)

window = QtWidgets.QMainWindow()
window.setGeometry(0,0,320,240)

label = QtWidgets.QLabel("Hello World!")

window.setCentralWidget(label)
window.show()

app.exec_()
```

With pyQT on AP

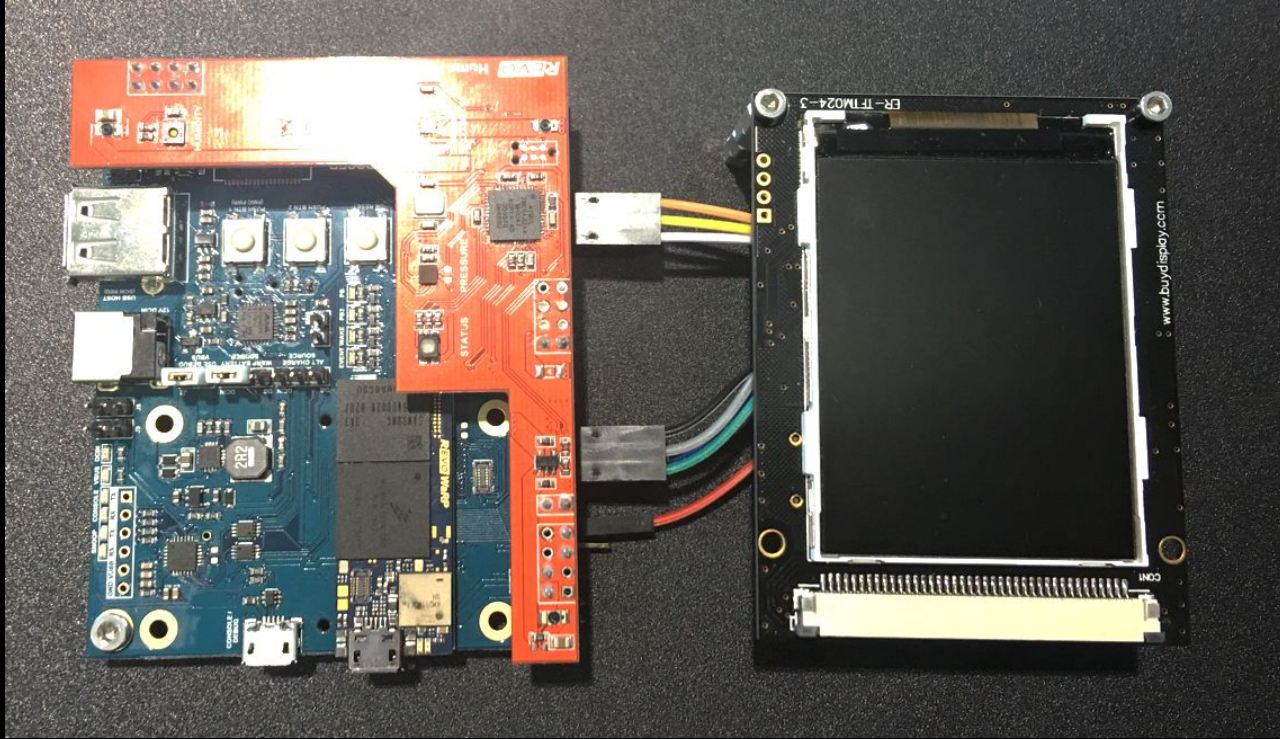


MCU code on same display

# Prototype 0x03

- › **Hardware:** Warp, ~~custom sensor board (hooked to the interposer pin outs)~~, small form factor custom daughter board
- › **Accessories:** Display, Battery
- › **Dev Tools:** ~~Interposer Board~~
- › **OS:** Yocto Linux
- › **I/O:** WiFi, Serial Gadget
- › **Software:** Python, Java, APIs

**Value:** proof of concept of an optimized IoT headful edge device

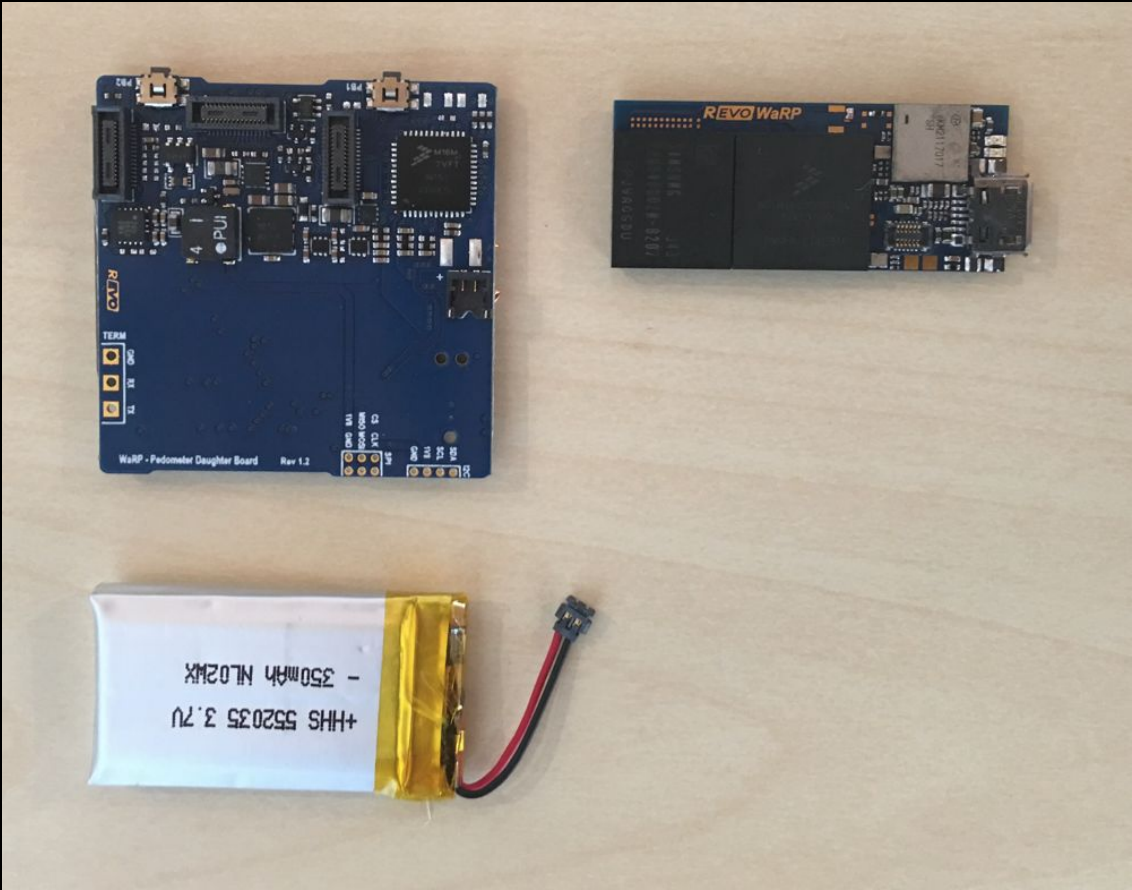


# Prototype 0x04

- › **Hardware:** Warp, #pedometer daughter board concept
- › **Accessories:** Display, Battery
- › **Dev Tools:** ~~Interposer Board~~
- › **OS:** ~~Yocto Linux~~, Android
- › **I/O:** WiFi, Serial Gadget, BT
- › **Software:** Java

**Value:** proof of concept of a #headful wearable device







# Productize it

- › In the workflow (from Getting Started to 0x03) you see definitively steps common to take concept to productization.

Such as:

- › IoT Sensor (like Nest)
- › Home Automation (like Amazon Echo)
- › eInk Reader/Signage (Kindle)
- › Medical Devices

# Availability

- › Direct from us
- › Shipping today
- › More coming soon

The screenshot displays the REVOTICS website interface. The top navigation bar includes the REVOTICS logo with the tagline "DESIGN CREATE INNOVATE", and menu items for STORE, PRODUCTS, SERVICES, and SUPPORT. A search bar and user icons are also present. The main content area is titled "Store > WaRP" and features a "SEARCH PRODUCTS" section with a search input field and a "Search" button. Below this is a "PRODUCT CATEGORIES" section listing "Interface Modules", "Micro Power Modules", and "WaRP". A "CART" section shows a "12V Boost Micro Power Module Voltage Regulator (24W Step-up)" with a quantity of 1 and a price of \$15.95, and a "Subtotal: \$15.95". There are "View Cart" and "Checkout" buttons. The main product grid displays six items:

- 350mAh Lithium Polymer Battery: \$4.99
- ED0605C4 E-Paper Display: \$40.00
- Hirose DF4DHC13.0-300C-0.4V[S1]-WaRP Daughterboard Connector: \$1.00
- WaRP - Mainboard: \$149.99
- WaRP EPD Development Adapter (Pre-release): \$40.00
- WaRP Interposer Development Board: \$49.95

Each product card includes an image, a title, a price, and "Add to cart" and "Show Details" buttons. A descriptive paragraph for WaRP is located above the product grid: "WaRP is an ultra small form-factor embedded platform with a hybrid architecture that enables rapid prototyping and customization of the platform. For more information see here." Below the grid, there are sorting and pagination options: "Sort by Default Order" and "Display 24 Products per page". The footer contains copyright information: "Copyright © 2015 Revolution Robotics, Inc. All Rights Reserved." and links for "Privacy Policy" and "Sales Terms".

# License

- › Hardware schematics and all documentation are licensed under a Creative Commons Attribution-ShareAlike 4.0 International License.
- › Operating systems are released under their respective licenses
- › No proprietary software on public codebase

# References

- › Mailing list: >warpx.io on Google group
- › Store: <http://revotics.com/store>
- › Community website: [www.warpx.io](http://www.warpx.io)
- › Documentation: [www.warpx.io/resources](http://www.warpx.io/resources)
- › This presentation: [www.warpx.io/resources](http://www.warpx.io/resources)
- › GitHub: <https://github.com/warpxboard>

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